

## FIXED POINTS OF MAPPINGS WITH DIMINISHING PROBABILISTIC ORBITAL DIAMETERS

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**Abstract.** In this paper we prove a fixed point theorem for a pair of mappings with probabilistic diminishing orbital diameters on Menger spaces and introduce the notion of generalized joint diminishing probabilistic orbital diameters (gjdpod) for a quadruplet of mappings.

### 1 Introduction

The notion of ‘diminishing orbital diameters’ (dod) was introduced by Belluce and Kirk [1]. Subsequently, Fisher [3], Huang, Huang and Jeng [4], Liu [7], Ranganathan, Srivastva and Gupta [9], Singh [10], Wong [12] etc. obtained some more results in this settings.

Istrăţescu and Săcuiu [5] introduced the concept of non-expansive mappings and mapping with ‘diminishing probabilistic orbital diameters’ (dpod) on probabilistic metric spaces (PM-spaces). Singh and Pant [11] have shown that a non-expansive mapping on PM-space having dpod has a fixed point. They have also investigated that the condition of non-expansiveness of the mapping may be relaxed to the condition of the mapping being with relatively compact orbits.

In this paper we introduce the notion of dpod and gjdpod for a pair of mappings and established a fixed point theorem. Subsequently, we introduced the concept of gjdpod for a quadruplet of mappings and prove a fixed point theorem. Some of the previously results of [7], [9], [10], [11] (in different settings) may be derived from our results.

#### 1.1 Preliminaries

**Definition 1.** [2]. Let  $A$  be a non-empty subset of  $X$ . The function  $D_A(\cdot)$  defined by

$$D_A(x) = \sup_{\varepsilon < x} \{ \inf_{u,v \in A} F_{u,v}(\varepsilon) \}$$

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is called the probabilistic diameter of  $A$ .

**Definition 2.** [2]. The function  $E_{A,B}(\cdot)$  defined by

$$E_{A,B}(\varepsilon) = \text{lub } t \{ \text{glb}_{x < \varepsilon} (\text{lub}_{u \in A} F_{u,v}(x)), (\text{glb}_{v \in B} \text{lub}_{u \in A} F_{u,v}(x)) \}$$

is called the probabilistic distance between  $A$  and  $B$ .

Let  $P : X \rightarrow X$  and  $u \in X$ , then  $O_P(u) = (u, Pu, P^2u, \dots)$  is called the orbit of  $u$  with respect to  $P$  and  $\overline{O_P(u)}$  denotes the closure of  $O_P(u)$ .

**Definition 3.** [5] Let  $P$  be a self map on a PM-space  $X$ .  $P$  is said to have dpod at  $u$  if for  $D_{O_P(P(u))}(\varepsilon) > 0$

$$\lim_{n \rightarrow \infty} D_{O_P(P^n(u))}(\varepsilon) > D_{O_P(u)}(\varepsilon)$$

where  $H$  is a distribution function.

We now introduce the following definitions :

**Definition 4.** A pair of mappings  $P, Q$  of a PM-space  $X$  is said to have diminishing probabilistic orbital diameters (dpod) if

$$\lim_{n \rightarrow \infty} E_{O_P(P_n(u)), O_Q(Q_n(u))}(\varepsilon) > E_{O_P(u), O_Q(u)}(\varepsilon), \varepsilon > 0,$$

for all  $u \in X$  with  $E_{O_P(P_n(u)), O_Q(Q_n(u))}(\varepsilon) \neq H$ .

**Definition 5.** A pair of mappings  $P, Q$  on a PM-space  $X$  is said to have generalized diminishing probabilistic orbital diameters (gdpod) if

$$\lim_{n \rightarrow \infty} E_{O_P(P_n(u)), O_Q(Q_n(v))}(\varepsilon) > E_{O_P(u), O_Q(v)}(\varepsilon), \varepsilon > 0,$$

for all  $u \in X$  with  $E_{O_P(P_n(u)), O_Q(Q_n(v))}(\varepsilon) \neq H$ .

It is clear that  $(P, Q)$  has a dpod if  $(P, Q)$  has a gpod. Also  $(P, P)$  has a dpod if and only if  $P$  has dpod.

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## 2 Main Result

**Theorem 6.** *Let  $P$  and  $Q$  are continuous self mappings of a compact Menger space. If the pair  $(P, Q)$  has a gdpod on  $X$ , then for each  $u, v \in X$ , there exists some subsequences  $\{P^{n_k}(u)\}$  of  $P_n(u)$  and  $\{Q^{n_k}(u)\}$  of  $Q_n(u)$  converge to a common fixed point of  $P$  and  $Q$ .*

*Proof.* Let  $u \in X$ ,  $L(u)$  denotes the set of all points of  $X$  which are the limits of the subsequences  $P_n(u)$ . Since  $L(u) \neq \emptyset$  because  $X$  is compact,  $L(u)$  is mapped into itself by  $P$ . Also  $L(u)$  is closed, so by Zorn's lemma there exists a minimal  $P$ -invariant non-empty subset  $A \subset L(u)$  such that  $A$  is closed and mapped into itself by  $P$ .

Similarly we can find a minimal  $Q$ -invariant non-empty subset  $B \subset L(v)$  such that  $B$  is closed and mapped into itself by  $Q$ . For  $u_0 \in A$ ,  $O_P(u_0)$  is mapped into itself by  $P$ . Therefore minimality of  $A$  implies that  $A = \overline{O_P(u_0)}$ . Similarly for  $v_0 \in B$ , we have  $B = \overline{O_Q(v_0)}$ .

We now prove that  $E_{A,B}(\varepsilon) = H$ ,  $\varepsilon > 0$ . Suppose  $E_{A,B}(\varepsilon) \neq H$ ,  $\varepsilon > 0$ . Since  $P, Q$  has a dpod, we have

$$E_{A,B}(\varepsilon) = E_{O_P(u_0), O_Q(v_0)}(\varepsilon) < \lim_{n \rightarrow \infty} E_{O_P(P_n(u_0)), O_Q(Q_n(v_0))}(\varepsilon)$$

This implies

$$E_{\overline{O_P(u_0)}, \overline{O_Q(v_0)}}(\varepsilon) < \lim_{n \rightarrow \infty} E_{\overline{O_P(P_n(u_0))}, \overline{O_Q(Q_n(v_0))}}(\varepsilon) = E_{A,B}(\varepsilon)$$

contradiction. Hence  $E_{A,B}(\varepsilon) = H$ , which implies that  $A = B = (w)$  (say). Then it is clear that  $w$  is a common fixed point of  $P$  and  $Q$ . If  $z$  is another fixed point of  $P$  and  $z \neq w$ . Then we have

$$\lim_{n \rightarrow \infty} E_{O_P(P_n(z)), O_Q(Q_n(w))}(\varepsilon) > E_{O_P(z), O_Q(w)}(\varepsilon), \varepsilon > 0,$$

$$\text{or } E_{z,w}(\varepsilon) > E_{z,w}(\varepsilon),$$

a contradiction. Hence  $w$  is a unique fixed point of  $P$ . Similarly, we may show that  $w$  is a unique fixed point of  $Q$ .

This completes the proof of the theorem □

**Remark 7.** *If in the above theorem condition gdpod is replaced by the condition dpod, then it no longer assures the existence of a common fixed point for  $P$  and  $Q$ . (see [7])*

**Corollary 8.** *Let  $P$  be a continuous self mapping of a compact Menger space  $X$ . If  $(P, P)$  has a gdpod, then  $P$  has a unique fixed point. Furthermore, for each  $u \in X$ , there exists some subsequences of  $P^n(u)$  converge to a unique fixed point of  $P$ .*

Pant, Dimri and Chandola [8] have introduced the concept of joint sequence of iterates for a quadruplet of mappings as follows:

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**Definition 9.** [8] Let  $B = (P, Q, S, T)$  be a quadruplet of self mappings on a PM-space  $X$ . For  $u_0$  in  $X$ , let  $Tu_n = QU_{n-1}$ , if  $n$  is odd and  $Tu_n = SQU_{n-1}$  if  $n$  is even, then the sequence

$$J_B(u_0) = \{u_0, Pu_0, QPu_0, SQPu_0, TSQPu_0, \dots\}$$

is called the joint sequence of iterates of  $B$  at  $u_0$

We now introduce the notion of gjdpod for a quadruplet of mappings in PM-space

$$\text{Let } \delta_u(\varepsilon) = \lim_{n \rightarrow \infty} D_{J_{B_n}(u)}(\varepsilon).$$

**Definition 10.**  $B$  will be called to have gjdpod at  $u$  if for  $D_{J_{B_n}(u)}(\varepsilon) \neq H, \varepsilon > 0$ ,

$$\delta_u(\varepsilon) > D_{J_B(u)}(\varepsilon).$$

**Theorem 11.** Let  $X$  be a compact Menger space and  $B = (P, Q, S, T)$  be a quadruplet of continuous self mappings on  $X$  such that  $B$  have gjdpod on  $X$ . Then for each  $u_0 \in X$ , a subsequence of  $J_B(u_0)$  converges to a common fixed point of  $P, Q, S$  and  $T$ .

*Proof.* For  $u_0 \in X$ , let  $A(u_0)$  denote the set of all points of  $X$  which are limit of subsequences of the sequence  $J_B(u_0)$ . Since  $X$  is compact,  $A(u_0) \neq \phi$  Also  $A(u_0)$  is closed and mapped into itself by  $P, Q, S$  and  $T$ . Let some subsequence of  $J_B(u_0)$  converge to a point  $u$  in  $X$ , so  $u \in A(u_0)$ . Further  $P, Q, S$  and  $T$  are continuous, therefore  $J_B(u_0) \subset A(u_0)$ . By Zorn's Lemma, there exists a minimal nonempty subset  $K \subset A(u_0)$  such that  $K$  is closed and mapped into itself by  $P, Q, S$  and  $T$ . Also for  $q_0 \in K$ ,  $J_B(q_0)$  is mapped into itself by  $P, Q, S$  and  $T$ . Therefore minimality of  $K$  implies that  $K = \overline{J_B(q_0)}$ . Suppose  $D_K(\varepsilon) \neq H, \varepsilon > 0$ . Since  $B$  have gjdpod, then we have

$$\delta_{q_0}(\varepsilon) > D_{J_B(q_0)}(\varepsilon).$$

This implies that  $D_{J_{B_n}(q_0)}(\varepsilon) > D_{J_B(q_0)}(\varepsilon)$ , for some integer  $n$ . Thus

$$D_{J_{B_n}(q_0)}(\varepsilon) > D_{J_B(q_0)}(\varepsilon), \varepsilon > 0$$

This shows that  $J_{B_n}(q_0)$  is a proper subset of  $K$ , contradicting the minimality of  $K$ . Hence  $D_K(\varepsilon) = H, \varepsilon > 0$  Thus  $K$  consists of a single point  $q_0$ . So we have  $P(q_0) = Q(q_0) = R(q_0) = S(q_0) = q_0$ . Therefore  $q_0$  is the common fixed point of  $P, Q, S$  and  $T$   $\square$

**Remark 12.** With  $Q = S = T = I$  (Identity mapping), the notion of gjdpod is same as dpod and then result of Kirk (Th. A, [6]) follow.

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**Remark 13.** *If any two of  $P, Q, S, T$  are taken as identity maps then gjdpod reduces to jdpod and the result of Singh and Pant (Th. 4, [11]) is obtained as corollary.*

**Remark 14.** *It is not necessary that any continuous mapping  $P$  in Theorem 11 has dpod on  $X$ , since in such a case it might be possible to obtain a family  $B$  of continuous self mappings on  $X$  such that  $B \cup P$  has a gjdpod (see, for illustration [9]).*

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