

Open Problems for Painlevé Equations

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Abstract. In this paper some open problems for Painlevé equations are discussed. In particular the following open problems are described: (i) the Painlevé equivalence problem; (ii) notation for solutions of the Painlevé equations; (iii) numerical solution of Painlevé equations; and (iv) the classification of properties of Painlevé equations.

Key words: Painlevé equations; open problems

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1 Introduction

The Painlevé equations are now regarded as “nonlinear special functions”, being nonlinear analogs of the classical special functions and form the core of “modern special function theory” [44, 68, 76, 138]. Indeed Iwasaki, Kimura, Shimomura and Yoshida [83] characterize the Painlevé equations as “the most important nonlinear ordinary differential equations” and state that “many specialists believe that during the twenty-first century the Painlevé functions will become new members of the community of special functions”. Subsequently this has happened as the Painlevé equations are a chapter in the NIST *Digital Library of Mathematical Functions* [118, Section 32]. The Painlevé functions have greatly expanded the role that the classical special functions, such as the Airy, Bessel, Hermite, Legendre and hypergeometric functions, started to play in the 19th century. Increasingly, as nonlinear science develops, people are finding that the solutions to an extraordinarily broad array of scientific problems, from neutron scattering theory, special solutions of partial differential equations such as nonlinear wave equations, fibre optics, transportation problems, combinatorics, random matrices, quantum gravity and to number theory, can be expressed in terms of solutions of the Painlevé equations.

The Painlevé equations (P_I–P_{VI}), whose solutions are called the Painlevé transcendents, are the nonlinear ordinary differential equations given by

$$\frac{d^2w}{dz^2} = 6w^2 + z, \quad (1.1)$$

$$\frac{d^2w}{dz^2} = 2w^3 + zw + \alpha, \quad (1.2)$$

$$\frac{d^2w}{dz^2} = \frac{1}{w} \left(\frac{dw}{dz} \right)^2 - \frac{1}{z} \frac{dw}{dz} + \frac{\alpha w^2 + \beta}{z} + \gamma w^3 + \frac{\delta}{w}, \quad (1.3)$$

$$\frac{d^2w}{dz^2} = \frac{1}{2w} \left(\frac{dw}{dz} \right)^2 + \frac{3}{2} w^3 + 4zw^2 + 2(z^2 - \alpha)w + \frac{\beta}{w}, \quad (1.4)$$

$$\frac{d^2w}{dz^2} = \left(\frac{1}{2w} + \frac{1}{w-1} \right) \left(\frac{dw}{dz} \right)^2 - \frac{1}{z} \frac{dw}{dz} + \frac{(w-1)^2}{z^2} \left(\alpha w + \frac{\beta}{w} \right) + \frac{\gamma w}{z} + \frac{\delta w(w+1)}{w-1}, \quad (1.5)$$

$$\begin{aligned} \frac{d^2w}{dz^2} &= \frac{1}{2} \left(\frac{1}{w} + \frac{1}{w-1} + \frac{1}{w-z} \right) \left(\frac{dw}{dz} \right)^2 - \left(\frac{1}{z} + \frac{1}{z-1} + \frac{1}{w-z} \right) \frac{dw}{dz} \\ &\quad + \frac{w(w-1)(w-z)}{z^2(z-1)^2} \left\{ \alpha + \frac{\beta z}{w^2} + \frac{\gamma(z-1)}{(w-1)^2} + \frac{\delta z(z-1)}{(w-z)^2} \right\}, \end{aligned} \quad (1.6)$$

where α, β, γ and δ are arbitrary constants. These six equations have attracted much attention for mathematicians and physicists during the past 40 years or so, though they were discovered by Painlevé, Gambier et al. in the late 19th and early 20th centuries, in an investigation of which second-order ordinary differential equations of the form

$$\frac{d^2w}{dz^2} = F \left(w, \frac{dw}{dz}, z \right), \quad (1.7)$$

where F is rational in w and dw/dz and locally analytic in z , having the property that their solutions have no movable branch points. They showed that there were fifty canonical equations of the form (1.7) with this property, now known as the *Painlevé property*, up to a Möbius (bilinear rational) transformation

$$W(\zeta) = \frac{a(z)w + b(z)}{c(z)w + d(z)}, \quad \zeta = \phi(z), \quad (1.8)$$

where $a(z), b(z), c(z), d(z)$ and $\phi(z)$ are locally analytic functions. Further Painlevé, Gambier et al. showed that of these fifty equations, forty-four can be reduced to linear equations, solved in terms of elliptic functions, or are reducible to one of six new nonlinear ordinary differential equations that define new transcendental functions, see Ince [81, Chapter 14].

Following Sakai [128] and Ohshima et al. [113] (see also [114]), P_{III} (1.3) can be classified into four cases:

- (i) if $\gamma\delta \neq 0$, which is known as $P_{\text{III}}^{(6)}$, then set $\gamma = 1$ and $\delta = -1$, without loss of generality, by rescaling w and z if necessary

$$\frac{d^2w}{dz^2} = \frac{1}{w} \left(\frac{dw}{dz} \right)^2 - \frac{1}{z} \frac{dw}{dz} + \frac{\alpha w^2}{z} + \frac{\beta}{z} + w^3 - \frac{1}{w}; \quad (1.9)$$

- (ii) if $\gamma = 0$ and $\alpha\delta \neq 0$ (or equivalently $\delta = 0$ and $\beta\gamma \neq 0$), which is known as $P_{\text{III}}^{(7)}$, then set $\alpha = 1$ and $\delta = -1$, without loss of generality

$$\frac{d^2w}{dz^2} = \frac{1}{w} \left(\frac{dw}{dz} \right)^2 - \frac{1}{z} \frac{dw}{dz} + \frac{w^2}{z} + \frac{\beta}{z} - \frac{1}{w}, \quad (1.10)$$

or if $\delta = 0$ and $\beta\gamma \neq 0$ set $\beta = -1$ and $\gamma = 1$

$$\frac{d^2w}{dz^2} = \frac{1}{w} \left(\frac{dw}{dz} \right)^2 - \frac{1}{z} \frac{dw}{dz} + \frac{\alpha w^2}{z} - \frac{1}{z} + w^3; \quad (1.11)$$

- (iii) if $\gamma = \delta = 0$ and $\alpha\beta \neq 0$, which is known as $P_{\text{III}}^{(8)}$, then set $\alpha = 1$ and $\beta = -1$, without loss of generality

$$\frac{d^2w}{dz^2} = \frac{1}{w} \left(\frac{dw}{dz} \right)^2 - \frac{1}{z} \frac{dw}{dz} + \frac{w^2}{z} - \frac{1}{z};$$

- (iv) if $\alpha = \gamma = 0$ (or equivalently $\beta = \delta = 0$) then the equation can be solved by quadratures and has no transcendental solutions.

In the sequel, we shall refer to equation (1.9) as P_{III} rather than $P_{\text{III}}^{(6)}$ since this is the generic case. Equation (1.10) is also known as the degenerate P_{III} , cf. [94, 95]. These different types of P_{III} were noted by Painlevé [123].

Similarly, P_{V} (1.5) can be classified into three cases:

- (i) if $\delta \neq 0$, then set $\delta = -\frac{1}{2}$, without loss of generality;
(ii) if $\delta = 0$ and $\gamma \neq 0$, then the equation is known as degenerate P_{V} (deg- P_{V})

$$\frac{d^2 w}{dz^2} = \left(\frac{1}{2w} + \frac{1}{w-1} \right) \left(\frac{dw}{dz} \right)^2 - \frac{1}{z} \frac{dw}{dz} + \frac{(w-1)^2}{z^2} \left(\alpha w + \frac{\beta}{w} \right) + \frac{\gamma w}{z}, \quad (1.12)$$

which is equivalent to P_{III} (1.9), cf. [67, Theorem 4.2], [76, Section 34];

- (iii) if $\gamma = 0$ and $\delta = 0$ then the equation can be solved by quadratures and has no transcendental solutions.

Each of the Painlevé equations can be written as a Hamiltonian system

$$\frac{dq}{dz} = \frac{\partial \mathcal{H}_J}{\partial p}, \quad \frac{dp}{dz} = -\frac{\partial \mathcal{H}_J}{\partial q},$$

for a suitable Hamiltonian function $\mathcal{H}_J(q, p, z)$ [84, 115, 116]. The function $\sigma(z) \equiv \mathcal{H}_J(q, p, z)$ satisfies a second-order, second-degree ordinary differential equation, known as the ‘‘Painlevé σ -equation’’, whose solution is expressible in terms of the solution of the associated Painlevé equation [84, 116]. The Painlevé σ -equations ($S_{\text{I}}-S_{\text{VI}}$) associated with $P_{\text{I}}-P_{\text{VI}}$ respectively are

$$\left(\frac{d^2 \sigma}{dz^2} \right)^2 + 4 \left(\frac{d\sigma}{dz} \right)^3 + 2z \frac{d\sigma}{dz} - 2\sigma = 0, \quad (1.13)$$

$$\left(\frac{d^2 \sigma}{dz^2} \right)^2 + 4 \left(\frac{d\sigma}{dz} \right)^3 + 2 \frac{d\sigma}{dz} \left(z \frac{d\sigma}{dz} - \sigma \right) = \frac{1}{4} \beta^2, \quad (1.14)$$

$$\left(z \frac{d^2 \sigma}{dz^2} - \frac{d\sigma}{dz} \right)^2 + \left[4 \left(\frac{d\sigma}{dz} \right)^2 - z^2 \right] \left(z \frac{d\sigma}{dz} - 2\sigma \right) + 4z\vartheta_\infty \frac{d\sigma}{dz} = 2\vartheta_0 z^2, \quad (1.15)$$

$$\left(\frac{d^2 \sigma}{dz^2} \right)^2 - 4 \left(z \frac{d\sigma}{dz} - \sigma \right)^2 + 4 \frac{d\sigma}{dz} \left(\frac{d\sigma}{dz} + 2\vartheta_0 \right) \left(\frac{d\sigma}{dz} + 2\vartheta_\infty \right) = 0, \quad (1.16)$$

$$\left(z \frac{d^2 \sigma}{dz^2} \right)^2 - \left[2 \left(\frac{d\sigma}{dz} \right)^2 - z \frac{d\sigma}{dz} + \sigma \right]^2 + 4 \prod_{j=1}^4 \left(\frac{d\sigma}{dz} + \kappa_j \right) = 0, \quad (1.17)$$

$$\frac{d\sigma}{dz} \left[z(z-1) \frac{d^2 \sigma}{dz^2} \right]^2 + \left[\frac{d\sigma}{dz} \left\{ 2\sigma - (2z-1) \frac{d\sigma}{dz} \right\} + \kappa_1 \kappa_2 \kappa_3 \kappa_4 \right]^2 = \prod_{j=1}^4 \left(\frac{d\sigma}{dz} + \kappa_j^2 \right), \quad (1.18)$$

where $\beta, \vartheta_0, \vartheta_\infty$ and $\kappa_1, \dots, \kappa_4$ are arbitrary constants.

Example 1.1. The Hamiltonian associated with P_{II} (1.2) is

$$H_{\text{II}}(q, p, z; \alpha) = \frac{1}{2} p^2 - \left(q^2 + \frac{1}{2} z \right) p - \left(\alpha + \frac{1}{2} \right) q \quad (1.19)$$

and so

$$\frac{dq}{dz} = p - q^2 - \frac{1}{2} z, \quad \frac{dp}{dz} = 2qp + \alpha + \frac{1}{2}, \quad (1.20)$$

see [84, 117]. Eliminating p in (1.20) then q satisfies P_{II} (1.2) whilst eliminating q yields

$$\frac{d^2p}{dz^2} = \frac{1}{2p} \left(\frac{dp}{dz} \right)^2 + 2p^2 - zp - \frac{(\alpha + \frac{1}{2})^2}{2p}, \quad (1.21)$$

which is known as P_{34} since is equivalent to equation XXXIV of Chapter 14 in [81]. Hence if q satisfies P_{II} (1.2) then $p = q' + q^2 + \frac{1}{2}z$ satisfies (1.21). Conversely if p satisfies (1.21) then $q = (p' - \alpha - \frac{1}{2})/(2p)$ satisfies P_{II} (1.2). Thus there is a one-to-one correspondence between solutions of P_{II} (1.2) and those of P_{34} (1.21). Further, the function $\sigma(z; \alpha) = H_{\text{II}}(q, p, z; \alpha)$ defined by (1.19), where q and p satisfy the system (1.20), then $\sigma(z; \alpha)$ satisfies (1.14). Conversely if $\sigma(z; \alpha)$ is a solution of (1.14), then

$$q(z; \alpha) = \frac{4\sigma''(z; \alpha) + 2\alpha + 1}{8\sigma'(z; \alpha)}, \quad p(z; \alpha) = -2\sigma'(z; \alpha),$$

with $' \equiv d/dz$, are solutions of (1.2) and (1.21), respectively [84, 115, 116, 117].

In this paper some open problems associated with the Painlevé equations are discussed. Specifically the following open problems are discussed.

1. Develop algorithmic procedures for the Painlevé equivalence problem: given an equation with the Painlevé property, how do we know if the equation can be solved in terms of a Painlevé equation (or a Painlevé σ -equation)?
2. Develop software for numerically studying the Painlevé equations which utilizes the fact that they are integrable equations solvable using isomonodromy methods.
3. Develop a notation for the Painlevé transcendents which takes into account the wide variety of solutions the Painlevé equations have.
4. Provide a complete classification and unified structure of the special properties which the Painlevé equations possess – the presently known results are rather fragmentary and non-systematic.

2 Painlevé equivalence problem

For a *linear* ordinary differential equation, if it can be solved in terms of known functions then the equation is regarded as being solved. Symbolic software such as MAPLE can easily find the solutions of the linear ordinary differential equations, as illustrated in the following example.

Example 2.1. Consider the linear equations

$$\frac{d^2v}{dz^2} + z^2v = 0, \quad \frac{d^2w}{dz^2} + e^{2z}w = 0,$$

which respectively have the solutions

$$v(z) = \sqrt{z} \left\{ C_1 J_{1/4} \left(\frac{1}{2}z^2 \right) + C_2 J_{-1/4} \left(\frac{1}{2}z^2 \right) \right\}, \quad w(z) = C_1 J_0(e^z) + C_2 Y_0(e^z),$$

with C_1 and C_2 arbitrary constants, $J_\nu(\zeta)$ and $Y_\nu(\zeta)$ Bessel functions.

It is a general property of linear ordinary differential equations that all singularities of their solutions are fixed. For example, solutions of the second-order equation

$$\frac{d^2w}{dz^2} + p(z) \frac{dw}{dz} + q(z)w = 0,$$

can only have singularities where the coefficients do, namely at the singularities of $p(z)$ and $q(z)$.

Definition 2.2. A *fixed singular point* of a solution of an ordinary differential equation is a singular point whose location does not vary with the particular solution chosen but depends only on the equation.

However it is not as simple for *nonlinear* ordinary differential equations which are quite different since, in general, their solutions can have both movable and fixed singularities.

Definition 2.3. A *movable singular point* of a solution of an ordinary differential equation is one whose location depends on the constant(s) of integration.

Currently there is no symbolic software available even to identify a nonlinear ordinary differential equation let alone find a solution, except for a few very simple examples. It is quite straightforward to determine whether a given (nonlinear) ordinary differential equation has the Painlevé property, e.g., using the Painlevé test [2, 3]; see also [1, 51, 98, 99].

Painlevé, Gambier et al. classified all ordinary differential equations of the form (1.7) with the Painlevé property, up to a Möbius transformation (1.8). Consequently, a given equation of the form (1.7) with the Painlevé property which is *not* in the list of fifty equations given by Ince [81, Chapter 14], how does one determine the Möbius transformation? If the equation is autonomous, or has a symmetry, then it has a first integral and one should be able to solve it in terms of elliptic equations, linear equations or by quadratures. If the equation is non-autonomous and does not possess a symmetry then it is likely to be solvable in terms of a Painlevé transcendent. The question is then to which one of the Painlevé equations (1.1)–(1.6) is the equation solvable in terms of?

We note that the solutions of some of the equations in the list given by Ince [81, Chapter 14] are solved in terms of Painlevé transcendents. For example, equation XX in the list, namely

$$\frac{d^2u}{dz^2} = \frac{1}{2u} \left(\frac{du}{dz} \right)^2 + 4u^2 + zu,$$

is solvable in terms of P_{II} since letting $u(z) = \sqrt{w(z)}$ yields (1.2) with $\alpha = 0$.

Example 2.4. Consider the equation

$$\frac{d^2w}{dz^2} = \frac{1}{w} \left(\frac{dw}{dz} \right)^2 - \frac{1}{z} \frac{dw}{dz} + w^3 - 1. \quad (2.1)$$

This equation can be shown to possess the Painlevé property, but is not in the list of fifty equations given in [81, Chapter 14]. Equation (2.1) arises from the symmetry reduction

$$u(x, t) = \ln w(z), \quad z = 2\sqrt{xt},$$

of the Tzitzéica equation [135, 136, 137]

$$u_{xt} = e^{2u} - e^{-u},$$

see also [64, 103, 104, 146]. Making the transformation

$$w(z) = x^{1/3}y(x), \quad z = \frac{3}{2}x^{2/3}, \quad (2.2)$$

in equation (2.1) yields

$$\frac{d^2y}{dx^2} = \frac{1}{y} \left(\frac{dy}{dx} \right)^2 - \frac{1}{x} \frac{dy}{dx} + y^3 - \frac{1}{x}, \quad (2.3)$$

which is the special case of $P_{\text{III}}^{(7)}$ (1.11) with $\alpha = 0$. The transformation (2.2) is suggested by the asymptotic expansions of (2.1) and (2.3)

$$\begin{aligned} w(z) &\sim 1 + \lambda z^{-1/2} \exp(-\sqrt{3}z), & \text{as } z \rightarrow \infty, \\ y(x) &\sim x^{-1/3} + \kappa x^{-2/3} \exp\left(-\frac{3}{2}\sqrt{3}x^{2/3}\right), & \text{as } x \rightarrow \infty, \end{aligned}$$

with λ and κ constants. Consequently one can derive the isomonodromy problem for equation (2.1) from that of equation (2.3).

Example 2.5. Consider the complex sine-Gordon equation

$$\nabla^2 \psi + \frac{(\nabla \psi)^2 \bar{\psi}}{1 - |\psi|^2} + \psi(1 - |\psi|^2) = 0, \quad (2.4)$$

where $\nabla \psi = (\psi_x, \psi_y)$, which is also known as the Pöhlmeier–Lund–Regge model [101, 102, 125]. This has a separable solution in polar coordinates given by $\psi(r, \theta) = \varphi_n(r)e^{in\theta}$, where $\varphi_n(r)$ satisfies the second-order equation

$$\frac{d^2 \varphi_n}{dr^2} + \frac{1}{r} \frac{d\varphi_n}{dr} + \frac{\varphi_n}{1 - \varphi_n^2} \left\{ \left(\frac{d\varphi_n}{dr} \right)^2 - \frac{n^2}{r^2} \right\} + \varphi_n(1 - \varphi_n^2) = 0, \quad (2.5)$$

which also arises in extended quantum systems [37, 38, 39], in relativity [74] and reflection coefficients for orthogonal polynomials on the unit circle [140, equation (3.13)]. Equation (2.5) can be shown to possess the Painlevé property, though is not in the list of 50 equations given in [81, Chapter 14]. Equation (2.5) can be transformed into P_V (1.5) in two different ways:

(i) the transformation

$$\varphi_n(r) = \frac{1 + u(z)}{1 - u(z)}, \quad \text{with } r = \frac{1}{2}z,$$

yields

$$\frac{d^2 u}{dz^2} = \left(\frac{1}{2u} + \frac{1}{u-1} \right) \left(\frac{du}{dz} \right)^2 - \frac{1}{z} \frac{du}{dz} + \frac{n^2(u-1)^2(u^2-1)}{8z^2u} - \frac{u(u+1)}{2(u-1)},$$

which is P_V (1.5) with $\alpha = \frac{1}{8}n^2$, $\beta = -\frac{1}{8}n^2$, $\gamma = 0$ and $\delta = -\frac{1}{2}$;

(ii) the transformation

$$\varphi_n(r) = \sqrt{\frac{v(z)}{v(z)-1}}, \quad \text{with } r = \sqrt{z},$$

yields

$$\frac{d^2 v}{dz^2} = \left(\frac{1}{2v} + \frac{1}{v-1} \right) \left(\frac{dv}{dz} \right)^2 - \frac{1}{z} \frac{dv}{dz} + \frac{n^2 v(v-1)^2}{2z^2} - \frac{v}{2z},$$

which is P_V (1.5) with $\alpha = \frac{1}{2}n^2$, $\beta = 0$, $\gamma = -\frac{1}{2}$ and $\delta = 0$, i.e., deg- P_V (1.12).

It is known that deg- P_V (1.12) is equivalent to P_{III} (1.9), cf. [76, Section 34]. Using this it can be shown that if $w(z)$ satisfies

$$\frac{d^2 w}{dz^2} = \frac{1}{w} \left(\frac{dw}{dz} \right)^2 - \frac{1}{z} \frac{dw}{dz} - \frac{2nw^2}{z} + \frac{2n+2}{z} + \gamma w^3 + \frac{\delta}{w},$$

which is P_{III} (1.9) with $\alpha = -2n$ and $\beta = 2n + 2$, then

$$\varphi_n(r) = \frac{\sqrt{-zw'(z) + zw^2(z) + (2n+1)w(z) + z}}{\sqrt{2zw(z)}}, \quad \text{with } r = z,$$

satisfies (2.5). Consequently solutions of equation (2.5) can be expressed in terms of solutions of both P_{III} (1.3) and P_{V} (1.5).

The function $\varphi_n(r)$ also satisfies the differential-difference equations

$$\frac{d\varphi_n}{dr} + \frac{n}{r}\varphi_n - (1 - \varphi_n^2)\varphi_{n-1} = 0, \quad (2.6a)$$

$$\frac{d\varphi_{n-1}}{dr} - \frac{n-1}{r}\varphi_{n-1} + (1 - \varphi_{n-1}^2)\varphi_n = 0. \quad (2.6b)$$

Solving (2.6a) for $\varphi_{n-1}(r)$ and substituting in (2.6b) yields equation (2.5), whilst eliminating the derivatives in (2.6), after letting $n \rightarrow n + 1$ in (2.6b), yields the difference equation

$$\varphi_{n+1} + \varphi_{n-1} = \frac{2n}{r} \frac{\varphi_n}{1 - \varphi_n^2}, \quad (2.7)$$

which is known as the discrete Painlevé II equation [108, 124, 140]. If $n = 1$ then equations (2.6) have the solution

$$\varphi_0(r) = 1, \quad \varphi_1(r) = \frac{C_1 I_1(r) - C_2 K_1(r)}{C_1 I_0(r) + C_2 K_0(r)},$$

where $I_0(r)$, $K_0(r)$, $I_1(r)$ and $K_1(r)$ are the imaginary Bessel functions and C_1 and C_2 are arbitrary constants. Then one can use (2.7) to determine $\varphi_n(r)$, for $n = 2, 3, \dots$. Using this Barashenkov and Pelinovsky [20] derive explicit multi-vortex solutions for the complex sine-Gordon equation (2.4).

The relationship between solutions of (2.5) and those of P_{III} (1.9), is illustrated in the following theorem.

Theorem 2.6. *If $\varphi_n(r)$ satisfies (2.5) then $w_n(r) = \varphi_{n+1}(r)/\varphi_n(r)$ satisfies*

$$\frac{d^2 w_n}{dr^2} = \frac{1}{w_n} \left(\frac{dw_n}{dr} \right)^2 - \frac{1}{r} \frac{dw_n}{dr} - \frac{2n}{r} w_n^2 + \frac{2n+2}{r} + w_n^3 - \frac{1}{w_n},$$

which is P_{III} (1.3) with parameters $\alpha = -2n$ and $\beta = 2n + 2$.

Proof. See Hisakado [79] and Tracy and Widom [132]. ■

Example 2.7. In their study of third-order ordinary differential equations, Muğan and Jrad [107] show that the equations

$$y^2 \frac{d^3 y}{dx^3} = 4y \frac{dy}{dx} \frac{d^2 y}{dx^2} - 3 \left(\frac{dy}{dx} \right)^3 + y^4 \frac{dy}{dx} + 4\kappa\mu x \left(y \frac{dy}{dx} - \kappa y^3 \right) - 4\kappa\mu y^2 + 3\mu \frac{dy}{dx}, \quad (2.8)$$

$$y \frac{d^3 y}{dx^3} = 2 \frac{dy}{dx} \frac{d^2 y}{dx^2} - 2y^2 \frac{d^2 y}{dx^2} + y^3 \frac{dy}{dx} + y^5 + \kappa \left(2 \frac{dy}{dx} + xy^3 + y^2 \right), \quad (2.9)$$

$$y \frac{d^3 y}{dx^3} = \frac{dy}{dx} \frac{d^2 y}{dx^2} - 2y^3 + \kappa y^2 - \frac{\kappa^2}{12} \left(x \frac{dy}{dx} - y \right), \quad (2.10)$$

where κ and μ are non-zero constants, have the Painlevé property. In [107] see equation (2.67) with $k_1 = 3\mu$, $k_2 = 0$, without loss of generality, and $k_3 = 4\kappa\mu$; equation (2.106) with $k_2 = \kappa$

and $k_3 = 0$, without loss of generality; and equation (4.14) with $k_1 = \kappa$ and $k_2 = 0$, without loss of generality¹. Levi, Sekera and Winternitz [100] show that (2.8), (2.10) and (2.10) have no symmetries and state that these equations are ‘‘candidates for new Painlevé transcendents’’; see equations (3.3), (3.4) and (3.4) in [100]. However, we show below, equation (2.8) can be solved in terms of P_{IV} (1.4) and equation (2.9) and (2.10) in terms of P_{34} (1.21).

Letting $y = \frac{1}{u} \frac{du}{dx}$ in equation (2.8) gives the tri-linear equation

$$\begin{aligned} & \left(\frac{du}{dx} \right)^2 \frac{d^4u}{dx^4} - 4 \frac{du}{dx} \frac{d^2u}{dx^2} \frac{d^3u}{dx^3} + 3 \left(\frac{d^2u}{dx^2} \right)^3 + \left(4\kappa\mu xu \frac{du}{dx} + 3\mu u^2 \right) \frac{d^2u}{dx^2} \\ & + 4\kappa\mu(\kappa + 1)x \left(\frac{du}{dx} \right)^3 - \mu(4\kappa + 3)u \left(\frac{du}{dx} \right)^2 = 0, \end{aligned}$$

which has the first integral, the bi-linear equation

$$\left(\frac{du}{dx} \right) \frac{d^3u}{dx^3} = \frac{3}{2} \left(\frac{d^2u}{dx^2} \right)^2 - (2\kappa^2\mu x^2 + K) \left(\frac{du}{dx} \right)^2 - 4\kappa\mu xu \frac{du}{dx} - \frac{3}{2}\mu u^2,$$

with K a constant of integration. Since $\frac{du}{dx} = uy$, then we obtain the second-order ordinary differential equation

$$\frac{d^2y}{dx^2} = \frac{3}{2y} \left(\frac{dy}{dx} \right)^2 + \frac{1}{2}y^3 - (2\kappa^2\mu x^2 - K)y - 4\kappa\mu x - \frac{3\mu}{2y},$$

which is the first integral of (2.8) and is not one of the 50 equations in Ince’s list. However, making the transformation

$$y(x) = \frac{\mu^{1/4}}{\kappa^{1/2}w(z)}, \quad z = \kappa^{1/2}\mu^{1/4}x,$$

yields P_{IV} (1.4) with parameters

$$\alpha = \frac{K}{\kappa\mu^{1/2}}, \quad \beta = -\frac{1}{2\kappa^2}.$$

Letting $y = \frac{1}{u} \frac{du}{dx}$ in equation (2.9) gives the tri-linear equation

$$u \frac{du}{dx} \frac{d^4u}{dx^4} = \left[u \frac{d^2u}{dx^2} + \left(\frac{du}{dx} \right)^2 \right] \frac{d^3u}{dx^3} + 2\kappa u \frac{d^2u}{dx^2} + \kappa x \left(\frac{du}{dx} \right)^3 - \kappa u \left(\frac{du}{dx} \right)^2,$$

which has the first integral

$$\frac{d^3u}{dx^3} + (\kappa x - 3C_1u) \frac{du}{dx} + 2\kappa u = 0, \tag{2.11}$$

with C_1 a constant of integration. Letting $u = v + \kappa x/C_1$ gives

$$\frac{d^3v}{dx^3} - 3C_1v \frac{dv}{dx} = 2\kappa x \frac{dv}{dx} + \kappa v.$$

¹The sign of the last term in (2.10) has been changed as there is a sign error in [107, equation (4.14)].

Multiplying this by v and integrating gives

$$v \frac{d^2 v}{dx^2} = \frac{1}{2} \left(\frac{dv}{dx} \right)^2 + C_1 v^3 + \kappa x v^2 + C_2,$$

with C_2 a constant of integration, which is equivalent to P_{34} (1.21), by rescaling the variables if necessary. Due to the relationship between P_{34} (1.21) and P_{II} (1.2) [67], solutions of equation (2.9) can be expressed in terms of solutions of P_{II} (1.2). Specifically if $w(z)$ is a solution of P_{II} (1.2), then

$$y(x) = -\kappa^{1/3} \left\{ 2w(z) + \frac{zw(z) + \alpha}{w'(z) + w^2(z)} \right\}, \quad x = -z/\kappa^{1/3},$$

where $' \equiv d/dz$ satisfies (2.9).

Letting $y = \frac{du}{dx}$ in equation (2.10) and integrating gives the third-order equation

$$\frac{d^3 u}{dx^3} + (24u - \kappa x) \frac{du}{dx} - \frac{\kappa^2 x}{12} = 0,$$

where the constant of integration has been set to zero, without loss of generality. Then making the transformation

$$u = -\frac{1}{4}v - \frac{1}{24}\kappa x,$$

yields

$$\frac{d^3 v}{dx^3} = (6v + 2\kappa x) \frac{dv}{dx} + \kappa v. \tag{2.12}$$

Multiplying this by v and integrating gives

$$v \frac{d^2 v}{dx^2} = \frac{1}{2} \left(\frac{dv}{dx} \right)^2 + 2v^3 + \kappa x v^2 + C,$$

with C a constant of integration, which is equivalent to P_{34} (1.21), by rescaling the variables if necessary.

Remark 2.8. We remark that equations (2.11) and (2.12), after rescaling the variables, arise as a scaling reduction of the Korteweg–de Vries equation [67] and as a nonclassical reduction of the Boussinesq equation [46].

Bureau [35] (see also [36, 40]) has also studied the classification of second order, second degree equations

$$\left(\frac{d^2 w}{dz^2} \right)^2 = F \left(w, \frac{dw}{dz}, z \right) + G \left(w, \frac{dw}{dz}, z \right) \frac{d^2 w}{dz^2}, \tag{2.13}$$

where F and G are rational in w and dw/dz and locally analytic in z . Cosgrove and Scoufis [58] have classified all equations with the Painlevé property for the special case of (2.13) when $G \equiv 0$, i.e.,

$$\left(\frac{d^2 w}{dz^2} \right)^2 = F \left(w, \frac{dw}{dz}, z \right),$$

where F is rational in w and dw/dz , locally analytic in z and not a perfect square. Cosgrove and Scoufis [58] solved the equations with the Painlevé property in terms of the Painlevé transcendents, elliptic functions, and solutions of linear equations, see also [53, 57, 129, 130]. Cosgrove [52] classified all equations that are of Painlevé type of the form

$$\left(\frac{d^2w}{dz^2}\right)^m = F\left(w, \frac{dw}{dz}, z\right), \quad m \geq 3,$$

where F is rational in w and dw/dz and locally analytic in z and solved the equations in terms of the first, second and fourth Painlevé transcendents, elliptic functions, or quadratures.

For various results on classifying classes of second-order ordinary differential equations, including Painlevé equations, see Babich and Bordag [12], Bagderina [13, 15, 16, 17, 18], Bagderina and Tarkhanov [19], Berth and Czichowski [22], Hietarinta and Dryuma [78], Kamran, Lamb and Shadwick [88], Kartak [90, 91, 92, 93], Kossovskiy and Zaitsev [97], Milson and Valiquette [106], Valiquette [139] and Yumaguzhin [145]. Most of these studies are concerned with the invariance of second-order ordinary differential equations of the form

$$\frac{d^2w}{dz^2} = F_3(w, z) \left(\frac{dw}{dz}\right)^3 + F_2(w, z) \left(\frac{dw}{dz}\right)^2 + F_1(w, z) \frac{dw}{dz} + F_0(w, z),$$

under the point transformations of the form

$$w = \psi(y, x), \quad z = \phi(y, x), \quad \frac{\partial(\psi, \phi)}{\partial(y, x)} \equiv \frac{\partial\psi}{\partial y} \frac{\partial\phi}{\partial x} - \frac{\partial\psi}{\partial x} \frac{\partial\phi}{\partial y} \neq 0.$$

Chazy [41, 42], Garnier [75] and Bureau [34] have obtained partial results on the classification of ordinary differential equations with the Painlevé property for third-order equations of the form

$$\frac{d^3w}{dz^3} = F\left(w, \frac{dw}{dz}, \frac{d^2w}{dz^2}, z\right), \quad (2.14)$$

where F is rational in w and its derivatives, and locally analytic in z . Despite the considerable length of these papers, only a very small proportion of the possible equations with the Painlevé property in each class were discovered. Further no new transcendents were discovered, i.e., every equation with the Painlevé property was shown to be solvable in terms of previously known equations, either Painlevé transcendents, elliptic functions or quadratures.

Most of the recent studies of Painlevé classification for third-order equations have concentrated on equations in the *Bureau polynomial class* where the function F in (2.14) is polynomial in w and its derivatives, rather than rational. Cosgrove [55, 56] classified third-order equations of this specific form with the Painlevé property and solved the equations in terms of the Painlevé transcendents, elliptic functions, solutions of linear equations or quadratures; see also [14, 54].

Open Problem 2.9. *Given an ordinary differential equation with the Painlevé property, how do we know whether it can be solved in terms of a Painlevé transcendent?*

3 Notation for Painlevé transcendents

Uniquely amongst the functions discussed in the DLMF [118], there is no special notation for the Painlevé transcendents, i.e., the solutions of the Painlevé equations. There are several functions in the DLMF whose notation involves P , or a variant, e.g., $P_n^{(\alpha, \beta)}(z)$ (Jacobi polynomials), $P_n(z)$ (Legendre polynomials), and $\wp(z)$ (Weierstrass elliptic functions). For linear equations, there are a finite number of linearly independent solutions, e.g., $\text{Ai}(z)$ and $\text{Bi}(z)$ for the Airy equation

$$\frac{d^2w}{dz^2} - zw = 0.$$

However, for nonlinear equations such as the Painlevé equations, the issue of notation is not as simple as there are numerous completely different solutions. Although second-order equations, there don't exist two "representative solutions". What is needed is some agreed notation for the Painlevé transcendents. In fact, unlike the linear case when the set of all solutions is a finite dimensional vector space, the set of all solutions of a Painlevé equation form a transcendental structure (a foliation travelling through a fibre bundle, each fibre of which is described by an affine Dynkin diagram) without any global coordinates which could be used as natural universal markers of the solutions. Such a notation would assist in the classification of properties of Painlevé equations.

For example, there are several different types of solutions of P_{II} (1.2).

- (i) The general solution of P_{II} is a transcendental function for *all* values of α and involves two arbitrary constants.
- (ii) Suppose that $w_k(z)$ is the solution of P_{II} with $\alpha = 0$, i.e.,

$$\frac{d^2 w_k}{dz^2} = 2w_k^3 + zw_k,$$

with the asymptotic behaviour

$$w_k(z) \sim k \operatorname{Ai}(z), \quad \text{as } z \rightarrow \infty, \quad (3.1)$$

where k is a real parameter and $\operatorname{Ai}(z)$ is the Airy function, which uniquely determines the solution. This family of solutions has different analytical properties on the real axis and have different asymptotic behaviours as $z \rightarrow -\infty$, depending on the parameter k .

- If $|k| < 1$, then $w_k(z)$ is the *Abowitz–Segur solution* [4, 131], which is pole-free on the real axis and as $z \rightarrow -\infty$ has oscillatory behaviour with algebraic decay given by

$$w_k(z) = d|z|^{-1/4} \sin\left(\frac{2}{3}|z|^{3/2} - \frac{3}{4}d^2 \ln|z| - \theta_0\right) + o(|z|^{-1/4}), \quad (3.2)$$

where the connection formulae $d^2(k)$ and $\theta_0(k)$, which relate the asymptotic behaviours (3.1) and (3.2) as $z \rightarrow \pm\infty$, are

$$\begin{aligned} d^2(k) &= -\pi^{-1} \ln(1 - k^2), \\ \theta_0(k) &= \frac{3}{2}d^2 \ln 2 + \arg\left\{\Gamma\left(1 - \frac{1}{2}id^2\right)\right\} + \frac{1}{4}\pi[1 - 2\operatorname{sgn}(k)], \end{aligned}$$

see [21, 48, 63].

- If $k = \pm 1$ then $w_k(z)$ is the *Hastings–McLeod solution* [77] which is monotonic, pole-free on the real axis and has algebraic growth as $z \rightarrow -\infty$ given by

$$w_{\pm 1}(z) = \pm \left(\frac{1}{2}|z|\right)^{1/2} + o(|z|^{1/2}). \quad (3.3)$$

- If $|k| > 1$ then $w_k(z)$ is a singular solution which has infinitely many poles on the negative real axis – see the numerical plot by Fornberg and Weideman [70, Fig. 12] – and has singular oscillatory behaviour as $z \rightarrow -\infty$ given by

$$w_k(z) = \frac{\sqrt{|z|}}{\sin\left\{\frac{2}{3}|z|^{3/2} + \beta \ln(8|z|^{3/2}) + \phi\right\}} + \mathcal{O}(|z|^{-1}), \quad (3.4)$$

where z bounded away from the singularities appearing in the denominator and the connection formulae $\beta(k)$ and $\phi(k)$ are

$$\beta(k) = \frac{1}{2}\pi^{-1} \ln(k^2 - 1), \quad \phi(k) = -\arg\left[\Gamma\left(\frac{1}{2}i\beta\right)\right] + \frac{1}{2}\pi[\operatorname{sgn}(k) - 1],$$

see [29, 89].

- Bothner [28] discusses the transition from the Ablowitz–Segur solution (3.2) and the singular solution (3.4) to the Hastings–McLeod solution (3.3) as $z \rightarrow -\infty$ and $|k| \rightarrow 1$. The transition asymptotics are expressed in terms of the Jacobi elliptic functions.
 - The case when $k = i\kappa$, with $\kappa \in \mathbb{R}$, in the boundary condition (3.1), known as the *pure imaginary Ablowitz–Segur solution*, is discussed by Its and Kapaev [82].
 - Bogatskiy, Claeys and Its [25] extended these results to discuss *complex Ablowitz–Segur solutions* in the case when $k \in \mathbb{C}$.
- (iii) For P_{II} with $\alpha \neq 0$, there are analogs of the Ablowitz–Segur and Hastings–McLeod solutions, known as the *quasi-Ablowitz–Segur solution* and the *quasi-Hastings–McLeod solution* [43, 59, 60]; see also [49, 70, 72, 134]. There is an extensive literature regarding the asymptotics for P_{II} (1.2) when $\alpha = 0$. There are significantly fewer asymptotic results in the case when $\alpha \neq 0$. Further, whilst the Ablowitz–Segur and Hastings–McLeod solutions have exponential decay as $z \rightarrow \infty$ given by (3.1), when $\alpha \neq 0$ then the solutions only have algebraic decay given by

$$w(z; \alpha) \sim -\alpha/z, \quad \text{as } z \rightarrow \infty.$$

For the quasi-Ablowitz–Segur solution when $\alpha \in (-\frac{1}{2}, \frac{1}{2})$, there exists a one-parameter family of real solutions $w(z)$ for $k \in (-\cos(\pi\alpha), \cos(\pi\alpha))$ with the following properties:

$$w(z) = B(z; \alpha) + k \operatorname{Ai}(z) [1 + \mathcal{O}(z^{-3/4})], \quad \text{as } z \rightarrow \infty,$$

and

$$w(z) = d|z|^{-1/4} \cos\left(\frac{2}{3}|z|^{3/2} - \frac{3}{4}d^2 \ln|z| + \phi\right) + \mathcal{O}(|z|^{-1}), \quad \text{as } z \rightarrow -\infty,$$

where $\operatorname{Ai}(z)$ is the Airy function and $B(z; \alpha)$ is given by

$$B(z; \alpha) \sim \frac{\alpha}{z} \sum_{n=0}^{\infty} \frac{a_n}{z^{3n}},$$

with coefficients a_n which are uniquely determined by the recurrence relation

$$a_{n+1} = (3n+1)(3n+2)a_n - 2\alpha^2 \sum_{j,k,\ell=0}^n a_j a_k a_\ell, \quad a_0 = 1.$$

The connection formulas are given by

$$\begin{aligned} d(k) &= \pi^{-1/2} \sqrt{-\ln(\cos^2(\pi\alpha) - k^2)}, \\ \phi(k) &= -\frac{3}{2}d^2 \ln 2 + \arg \Gamma\left(\frac{1}{2}id^2\right) - \frac{1}{4}\pi - \arg(-\sin(\pi\alpha) - ki), \end{aligned}$$

see Dai and Hu [59, 60]. For the quasi-Hastings–McLeod solution, Claeys, Kuijlaars and Vanlessen [43] show that there exists a unique solution which is pole-free on the real axis with the asymptotic behaviours

$$\begin{aligned} w(z) &\sim -\alpha/z, & z &\rightarrow +\infty, \\ w(z) &\sim \sqrt{\frac{1}{2}|z|}, & z &\rightarrow -\infty; \end{aligned}$$

see also [59, 60].

- (iv) Special function solutions of P_{II} arise if and only if $\alpha = n + \frac{1}{2}$, with $n \in \mathbb{Z}$, which involve one arbitrary constant [73]. These are expressed in terms of the $n \times n$ Wronskian determinant

$$\tau_n(z; \vartheta) = \det \left[\frac{d^{j+k}}{dz^{j+k}} \varphi(z; \vartheta) \right]_{j,k=0}^{n-1}, \quad n \geq 1,$$

where

$$\varphi(z; \vartheta) = \cos(\vartheta) \operatorname{Ai}(\zeta) + \sin(\vartheta) \operatorname{Bi}(\zeta), \quad \zeta = -2^{-1/3}z,$$

with $\operatorname{Ai}(\zeta)$ and $\operatorname{Bi}(\zeta)$ the Airy functions and ϑ an arbitrary constant; see also the recent studies [45, 61].

- (v) Rational solutions of P_{II} exist if and only if $\alpha = n$, with $n \in \mathbb{Z}$, which involve no arbitrary constants [141, 143]. These solutions are expressed in terms of polynomials $Q_n(z)$ of degree $\frac{1}{2}n(n+1)$, now known as the *Yablonskii–Vorob’ev polynomials*, which are defined through the recurrence relation (a second-order, bilinear differential-difference equation)

$$Q_{n+1}Q_{n-1} = zQ_n^2 - 4 \left[Q_n \frac{d^2Q_n}{dz^2} - \left(\frac{dQ_n}{dz} \right)^2 \right],$$

with $Q_0(z) = 1$ and $Q_1(z) = z$. Clarkson and Mansfield [47] investigated the locations of the roots of the Yablonskii–Vorob’ev polynomials in the complex plane and showed that these roots have a very regular, approximately triangular structure; the term “approximate” is used since the patterns are not exact triangles as the roots lie on arcs rather than straight lines. Bertola and Bothner [24] and Buckingham and Miller [32, 33] have studied the Yablonskii–Vorob’ev polynomials $Q_n(z)$ in the limit as $n \rightarrow \infty$ and shown that the roots lie in a “triangular region” with elliptic sides which meet with interior angle $\frac{2}{3}\pi$.

- (vi) There exist tronquée and tri-tronquée solutions of P_{II} , which are pole-free in sectors of the complex plane [30, 31]; see also [23, 80, 85, 86, 105, 111].

Open Problem 3.1. *Develop a notation for the Painlevé transcendents which takes into account the wide variety of solutions the Painlevé equations have.*

4 Numerical solution of Painlevé equations

Numerical analysis of the Painlevé equations presents novel challenges: in particular, in contrast to the classical special functions, where the linearity of the equations greatly simplifies the situation, each problem for the nonlinear Painlevé equations arises essentially anew. Ideally what is needed is reliable, easy to use software to compute numerically the solutions of the Painlevé equations. On the other hand, Painlevé transcendents, being solutions of *integrable* nonlinear equations, have much global information available about them. The software should be in the form of a living document where new numerical problems can be addressed by a pool of experts as they arise, as well as providing access to existing software. At the technical level, how does one combine asymptotic information about the solutions obtained from the Riemann–Hilbert problem, together with efficient numerical codes in order to compute the solution $w(z)$ at finite values of z ? A comprehensive analysis presents many challenges, conceptual, philosophical and technical.

Deift [62] wrote:

Writing useful numerical software for such nonlinear equations [i.e., the Painlevé equations] presents many challenges, conceptual, philosophical and technical. Without the help of linearity, it is not at all clear how to select a broad enough class of “representative problems”.

Numerical simulations of the Painlevé equations given in [44, 45] were obtained using MAPLE using the `DEplot` command with option `method=dverk78`, which finds a numerical solution using a seventh-eighth order continuous Runge–Kutta method. This is relatively simple to use, gives plots of solutions quickly with accuracy better than the human eye can detect, and generally works fine for initial value problems.

Some recent numerical computations of Painlevé equations include: a pole field solver using Padé approximations [65, 66, 69, 70, 71, 126, 127]; numerical Riemann–Hilbert problems [119, 120, 122, 121, 133, 142]; Fredholm determinants [26, 27]; Padé approximations [110, 112, 144]; pole elimination [5, 6, 7, 8, 9, 10, 11]; a multidomain spectral method [96].

Open Problem 4.1.

- *The Runge–Kutta method, and variants, are standard ODE solvers. Can we do better for integrable equations such as the Painlevé equations?*
- *Painlevé equations are “integrable” and solvable by the isomonodromy method through an associated Riemann–Hilbert problem. How can we use this in the development of software for studying the Painlevé equations numerically?*
- *It is well known that there are discrete Painlevé equations, which are integrable discrete equations that tend to the associated Painlevé equations in an appropriate continuum limit. Should we use a “integrable discretization” of the Painlevé equations?*

5 Classification of properties of Painlevé equations

The Painlevé equations are known to have a cornucopia of properties such as: a Hamiltonian representation; exact solutions (rational solutions, algebraic solutions, solutions in terms of classical special solutions); Bäcklund transformations (which relate two solutions of a Painlevé equation); associated isomonodromy problems (which are Lax pairs that express the Painlevé equation as the compatibility of two linear systems); and asymptotic approximations in the complex plane, with associated connection formulae relating the asymptotics. For details see [44, 50, 68, 76, 83, 87, 109] and the references therein.

Open Problem 5.1. *A complete classification and a unifying structure for these properties is needed as the presently known results are rather fragmentary and non-systematic.*

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